



Method	Species for which applications have been demonstrated	Seminal publication(s)	CTM usage required	Required input data	Computation al burden	Uncertainty*** and accuracy****	Source- category distinction
Mass Balance	SO <sub>x</sub> , NO <sub>x</sub> , NH <sub>3</sub>	(Beirle <i>et al.,</i> 2003, 2019)**	no	VCD, Windspeed, species lifetime	Low (~ <u>hour,</u> <u>several</u> CPU cores)	High uncertainty and very accurate (~40-65%, (Beirle <i>et al.</i> , 2019))	Limited
Gaussian plume	CO2, <u>SO</u> x, NO <sub>x</sub> , NH3	(Fioletov <i>et al.,</i> 2011, 2020)	no	VCD, Windspeed, species lifetime	Moderate (~ <u>hours,</u> <u>several</u> CPU cores)	Medium uncertainty and accuracy (~30-40%, (Dammers <i>et al.</i> , 2019))	Limited
(Ensemble / Adjustment) Kalman Filter	Chlorofluorocarbons, isoprene, O3, CO, CO2, <u>SO</u> x, <u>PM(</u> 2.5), NOx, NH3,	(Mijling and Van Der A, 2012; Ding <i>et al.</i> , 2020)	yes	VCD, CTM input*	<u>High(</u> ~days to weeks using many CPU cores)	Low uncertainty and accurate (~20%, (Ding <i>et</i> <i>al.</i> , 2020))	Yes
Adjoint based methods	<u>РМ(</u> 2.5), СН4,О3, СО, СО2, <u>SO</u> x, NOx, NH3	(Bergamaschi <i>et</i> <i>al.,</i> 2000, 2010)	yes	VCD, CTM input*	<u>High(</u> weeks using many CPU cores)	Low uncertainty (~10- 15%, (Cooper <i>et al.</i> , 2017)) Highly accurate (~10-15%, (Cooper <i>et al.</i> , 2017))	Yes



From dropdown, GeoJSON or shape file, select on map

1. Select region



Südpazifik







Venedig Verona



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